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N. Jayanthi

Department of EEE, Mother Theresa Institute of Engineering and Technology, A.P

C.S. Chaithanya

Department of EEE, Mother Theresa Institute of Engineering and Technology, A.P

C. Kalyankumar

Department of EEE, Mother Theresa Institute of Engineering and Technology, A.P

D. Harika

Department of EEE, Mother Theresa Institute of Engineering and Technology, A.P

G. Sravani

Department of EEE, Mother Theresa Institute of Engineering and Technology, A.P

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I. Introduction

Due to climate change's concerns, scientists and researchers are looking at fossil fuel alternatives in order to lower carbon dioxide emissions. One practical approach to lowering emissions and saving money in the automotive sector today is the use of electric cars. Electric vehicles (EVs) not only reduce noise pollution but also reduce emissions of harmful gases including carbon monoxide and nitrogen oxide [1]. In addition, charging an EV's battery at night helps the grid maintain a more stable load and lower overall costs since it occurs outside of the peak demand period [2]. It is important to use an efficient technique to realise signals transfer [3] between the transmission control unit (TCU) and other subsystems in an EV, such as the motor control unit (MCU) and battery management system (BMS). Because of its high reliability and high transmission baud rate, the Controller Area Network (CAN) bus is one approach that is commonly recognised by both manufacturers and researchers as being suitable for usage in EVs for the purpose of data transfer [4]. Fig. 1.

Electric vehicle powertrain

Authors

N.V. Kishore Kumar

Department of EEE, Mother Theresa Institute of Engineering and Technology, A.P

N. Jayanthi

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C.S. Chaithanya

Department of EEE, Mother Theresa Institute of Engineering and Technology, A.P

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